

A Local Temporal Difference Code for Distributional Reinforcement Learning

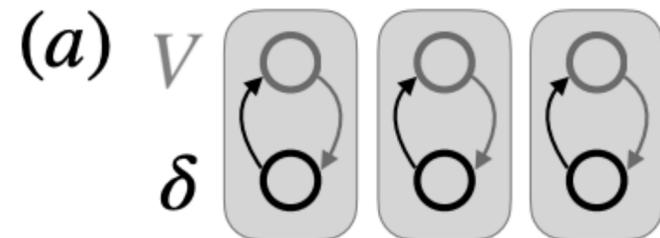
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Traditional

$$V(s_t) \leftarrow V(s_t) + \alpha \delta(t)$$
$$\delta(t) = r_t + \gamma V(s_{t+1}) - V(s_t)$$

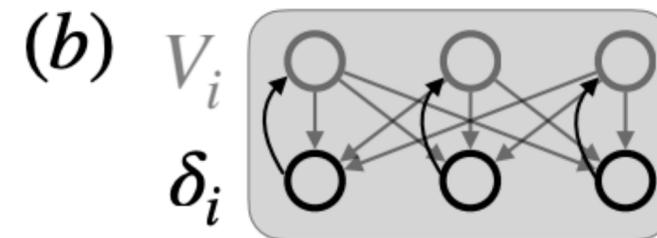
$$V(s) \rightarrow E \left[\sum_{\tau=0}^{\infty} \gamma^{\tau} r_{t+\tau} \mid s_t = s \right]$$



Distributional

$$V_i(s_t) \leftarrow V_i(s_t) + \alpha_i^+ \delta_i(t) \quad \text{if } \delta_i(t) > 0$$
$$V_i(s_t) \leftarrow V_i(s_t) + \alpha_i^- \delta_i(t) \quad \text{if } \delta_i(t) < 0$$
$$\delta_i(t) = r_t + \gamma \tilde{V}(s_{t+1}) - V_i(s_t)$$

But sampling from value distribution is not local.



Laplace code on discount factor

$$V_\gamma(s_t) \leftarrow V_\gamma(s_t) + \alpha \delta_\gamma(t)$$

$$\delta_\gamma(t) = r_t + \gamma V_\gamma(s_{t+1}) - V_\gamma(s_t)$$

$$V_\gamma(s_t) \rightarrow E \left[\sum_{\tau=0}^{\infty} \gamma^\tau r_{t+\tau} \mid s_t \right] = \sum_{\tau=0}^{\infty} \gamma^\tau E[r_{t+\tau} \mid s_t]$$

Discrete:

$$Z^{-1} \{V_\gamma(s_t)\}_{\gamma \in (0,1)} = \{E[r_{t+\tau} \mid s_t]\}_{\tau=0}^{\infty}$$

Continuous:

$$V_\gamma(s_t) \rightarrow \int_0^{\infty} e^{-\tau(-\log \gamma)} E[r_{t+\tau} \mid s_t] d\tau$$

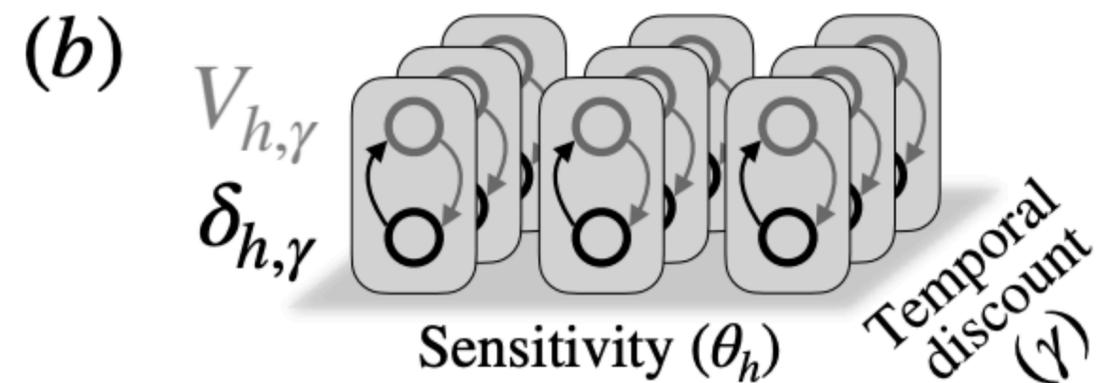
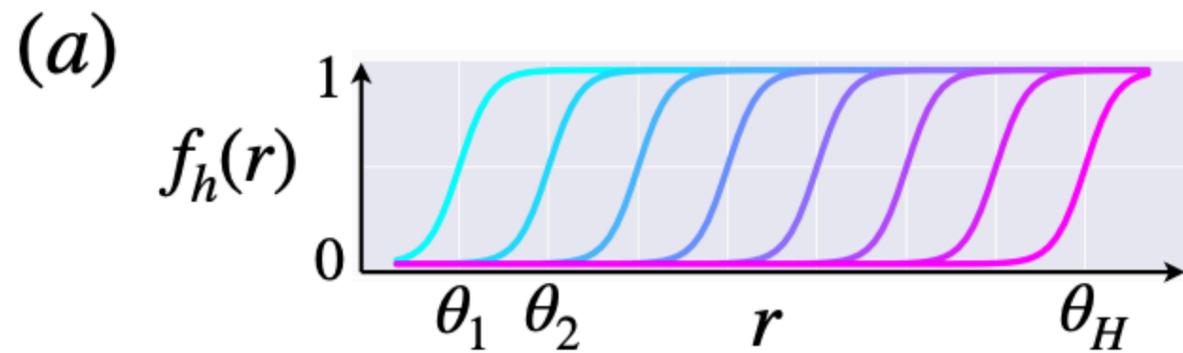
$$\mathcal{L}^{-1} \{V_\gamma(s_t)\}_{\gamma \in (0,1)} = \{E[r_{t+\tau} \mid s_t]\}_{\tau > 0}$$

Linear readout: $\mathbf{L}^{-1} [V_{\gamma_1}(s_t), \dots, V_{\gamma_N}(s_t)] = [E[r_{t+0} \mid s_t], \dots, E[r_{t+T} \mid s_t]]$

Laplace code on reward sensitivity

$$V_{h,\gamma}(s_t) \leftarrow V_{h,\gamma}(s_t) + \alpha \delta_{h,\gamma}(t)$$

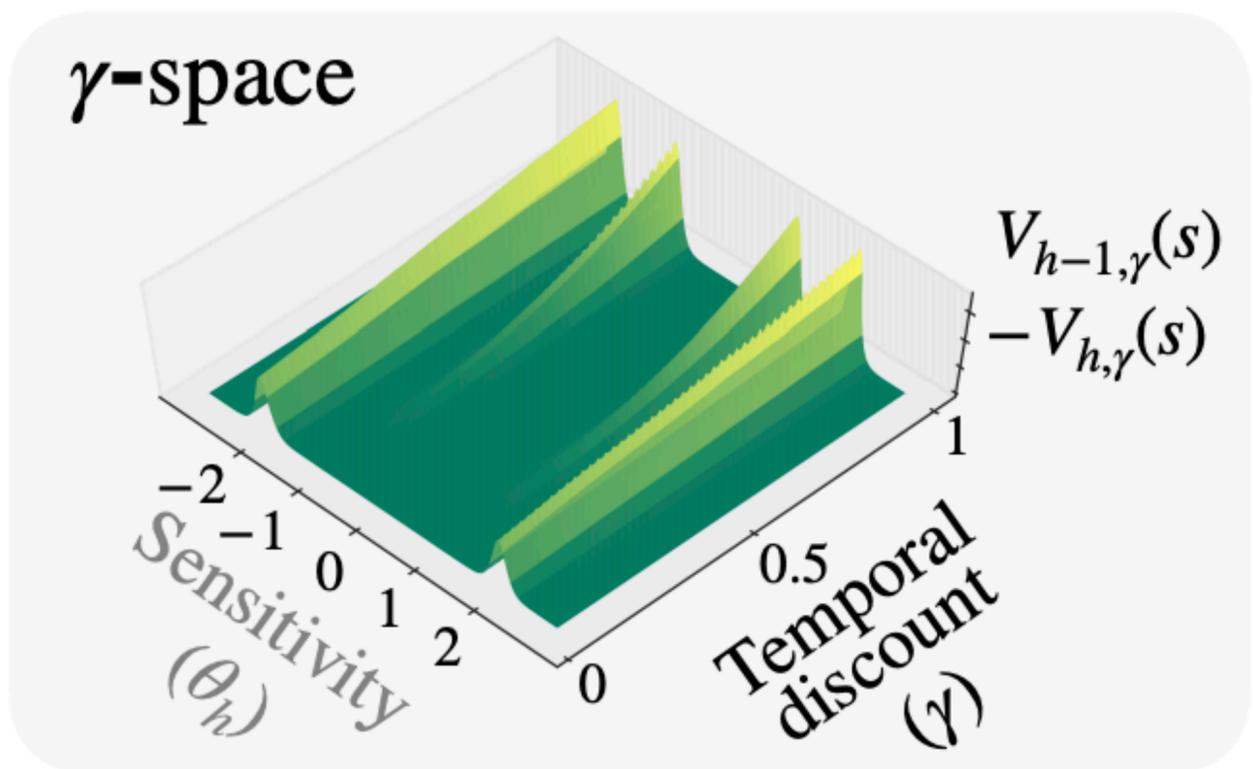
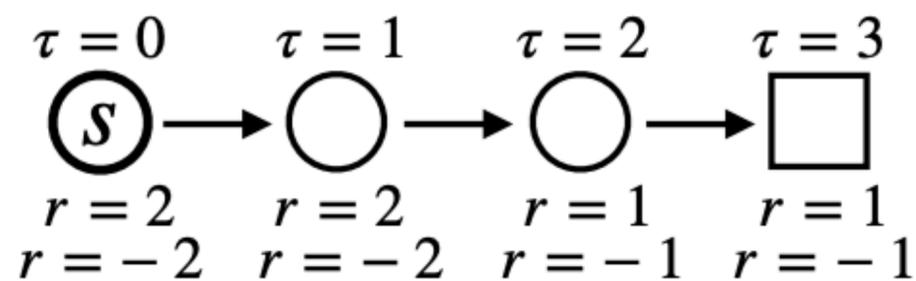
$$\delta_{h,\gamma}(t) = f_h(r_t) + \gamma V_{h,\gamma}(s_{t+1}) - V_{h,\gamma}(s_t)$$



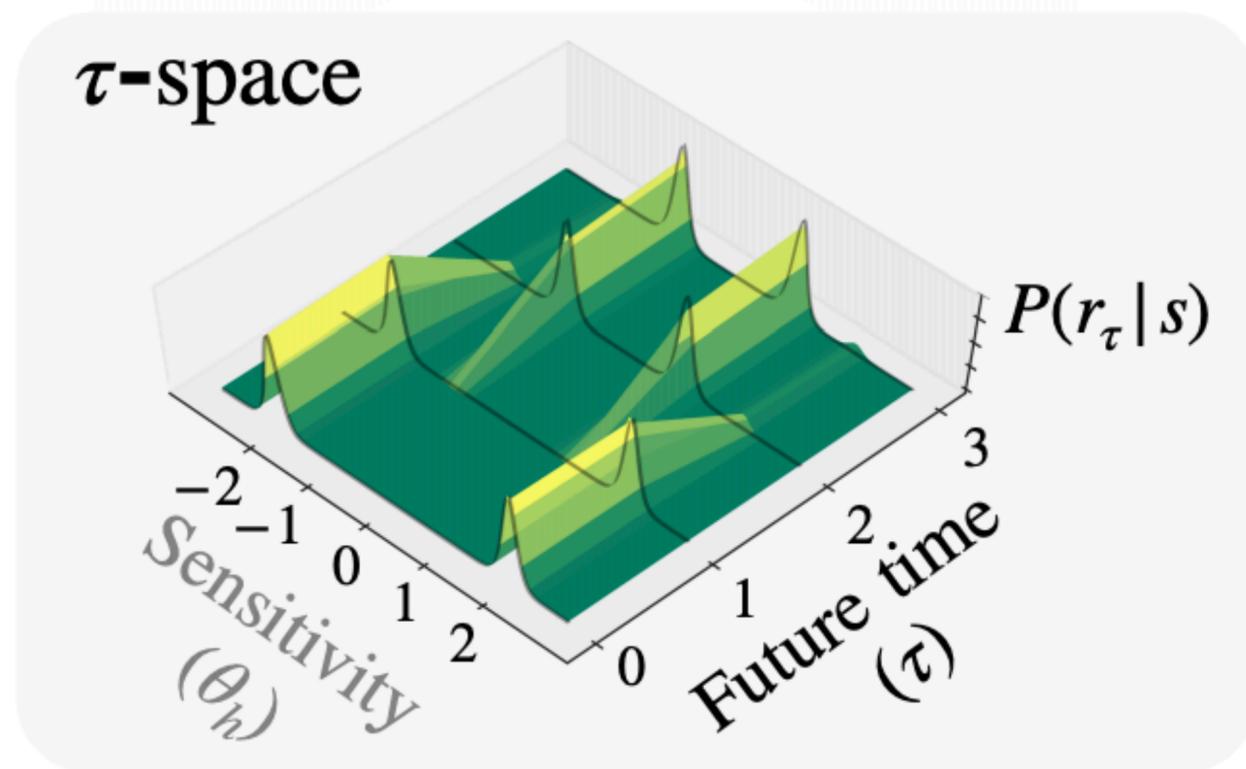
$$\begin{aligned} V_{h,\gamma}(s_t) &\rightarrow E\left[\sum_{\tau=0}^{\infty} \gamma^{\tau} f_h(r_{t+\tau}) \mid s_t\right] = \sum_{\tau=0}^{\infty} \gamma^{\tau} E[f_h(r_{t+\tau}) \mid s_t] \\ &= \sum_{\tau=0}^{\infty} \gamma^{\tau} E[H(r_{t+\tau} - \theta_h) \mid s_t] = \sum_{\tau=0}^{\infty} \gamma^{\tau} P(r_{t+\tau} > \theta_h \mid s_t) \end{aligned}$$

$$\mathbf{L}^{-1}[V_{h,\gamma_1}(s_t), \dots, V_{h,\gamma_N}(s_t)] = [P(r_{t+0} > \theta_h \mid s_t), \dots, P(r_{t+T} > \theta_h \mid s_t)]$$

TD learning (Eq. 10)



\mathbf{L}^{-1}



What can this code recover?

$$E \left[\sum_{\tau=0}^{\infty} \tilde{\gamma}^{\tau} r_{t+\tau} \mid s_t \right] = \sum_{\tau=0}^{\infty} \tilde{\gamma}^{\tau} \sum_r r P(r_{t+\tau} = r \mid s_t)$$

$$E \left[\sum_{\tau=0}^{\infty} \tilde{\gamma}^{\tau} r_{t+\tau} \mid s_t \right] = \sum_{h=1}^H (V_{h-1, \tilde{\gamma}}(s_t) - V_{h, \tilde{\gamma}}(s_t)) \theta_h$$

$$P \left(\sum_{\tau=0}^T \tilde{\gamma}^{\tau} r_{t+\tau} = V \mid s_t \right) = (1 - \delta_{(V,0)}) \sum_{\tau=0}^T P(r_{t+\tau} = \tilde{\gamma}^{-\tau} V \mid s_t)$$

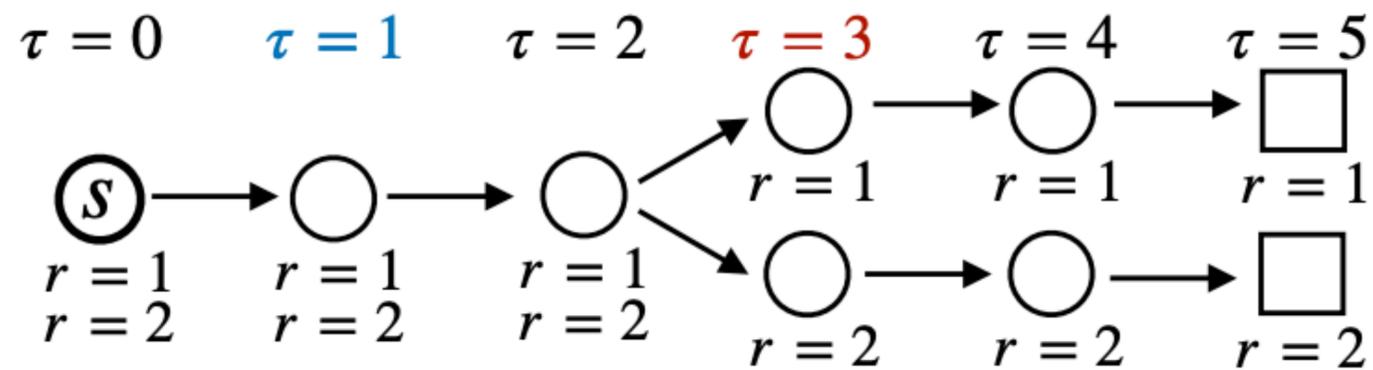
However, notice that this approach recovers the reward distribution evolution but not the value distribution since reward might be correlated across time.

Laplace code on temporal discount

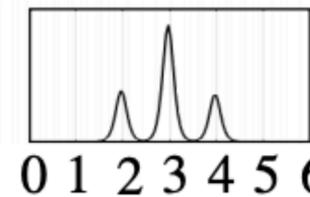
$$R_t^n = r_t + \dots + \tilde{\gamma}^n r_{t+n}$$

$$V_{h,\gamma,n}(s_t) \leftarrow V_{h,\gamma,n}(s_t) + \alpha \delta_{h,\gamma,n}(t+n)$$

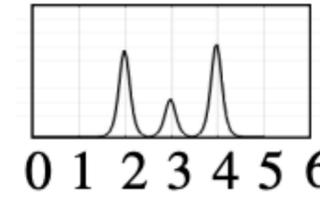
$$\delta_{h,\gamma,n}(t+n) = f_h(R_t^n) + \gamma V_{h,\gamma,n}(s_{t+1}) - V_{h,\gamma,n}(s_t)$$

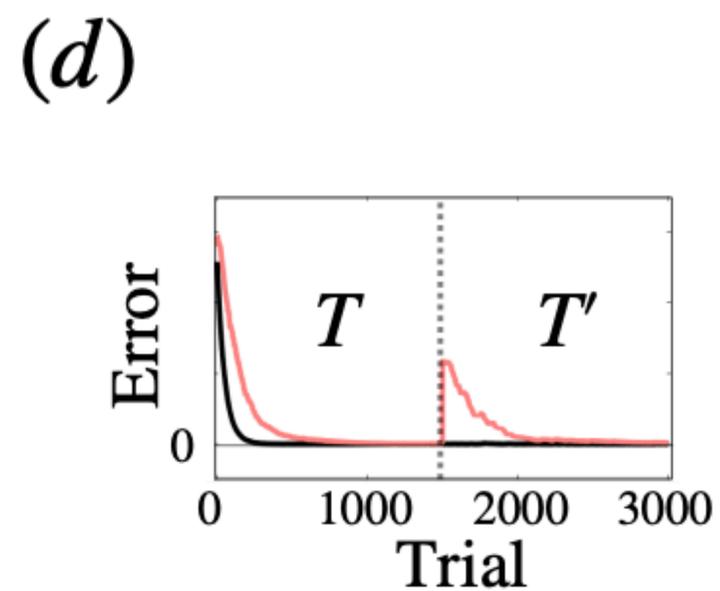
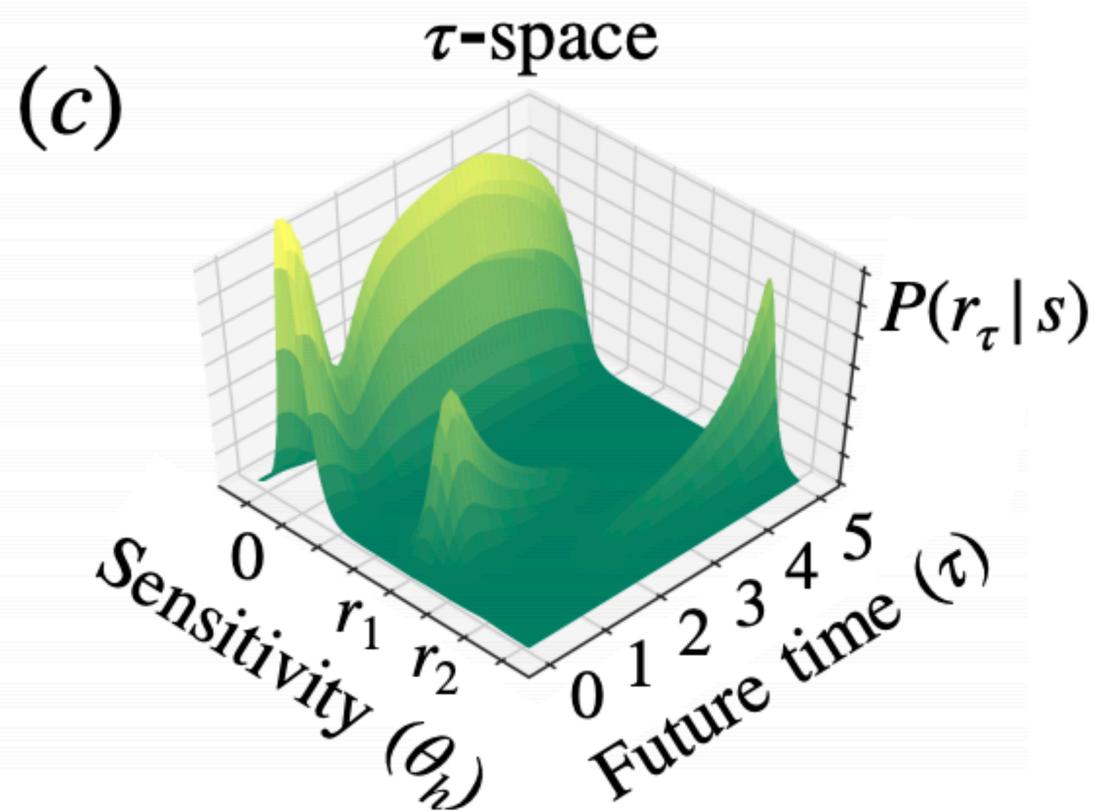
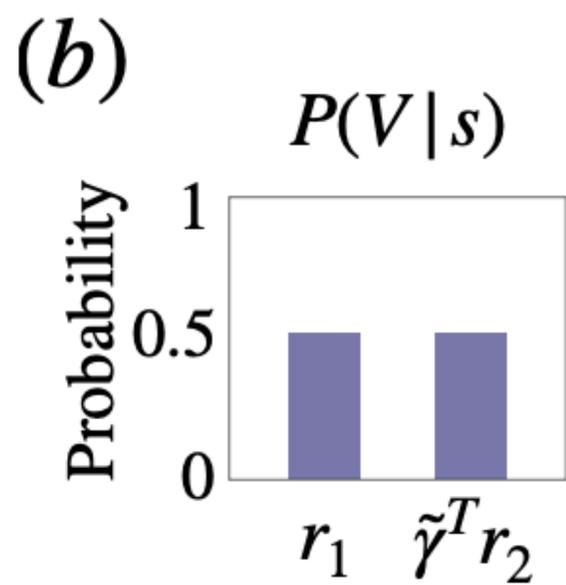
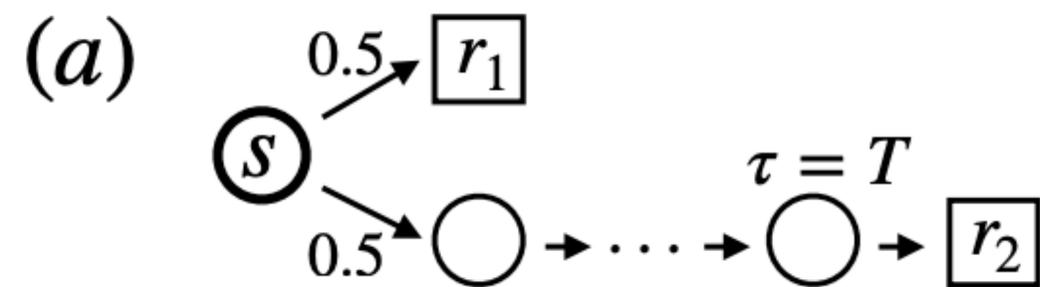


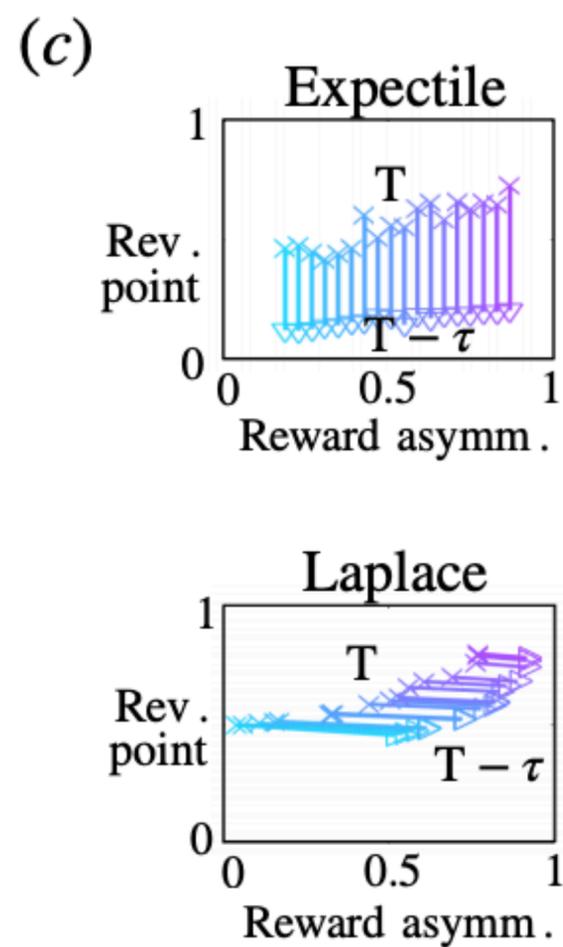
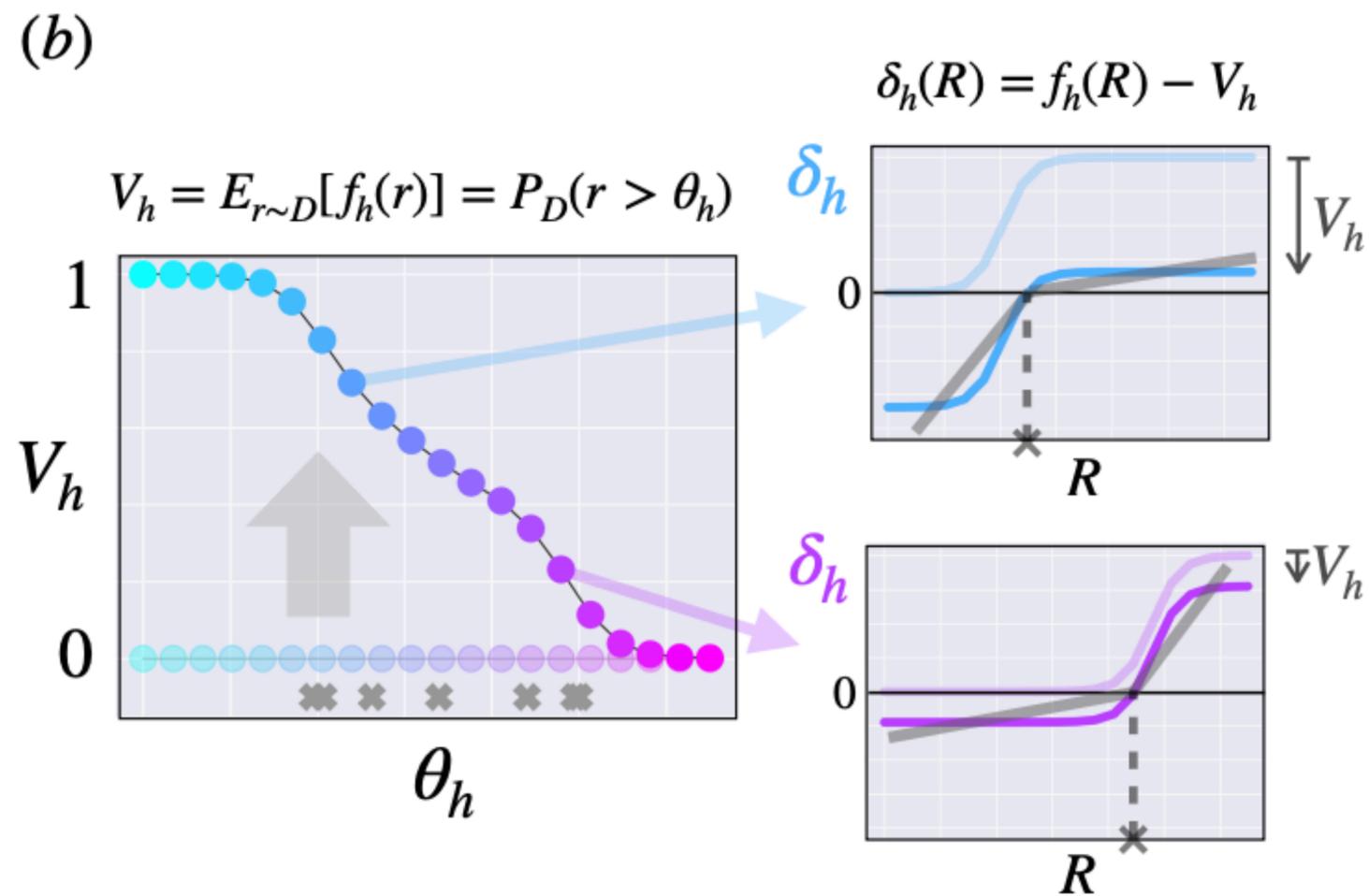
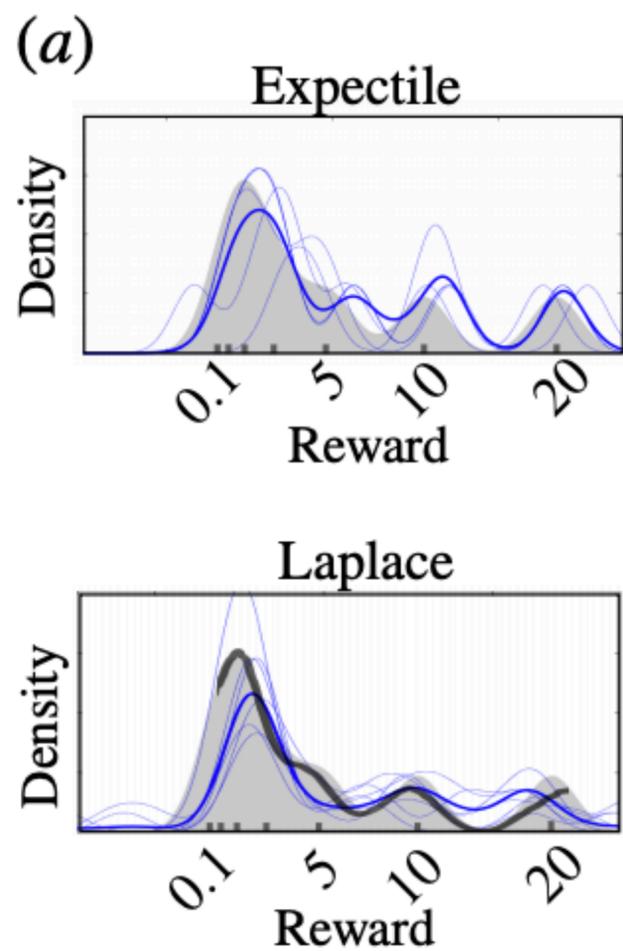
$$P(R_{\tau \approx 1}^{n=2} | s)$$



$$P(R_{\tau \approx 3}^{n=2} | s)$$







Connection to successor representation

$$[SR^\gamma(s)]_{s'} = E \left[\sum_{\tau=0}^{\infty} \gamma^\tau \delta_{(s', s_{t+\tau})} \mid s_t = s \right] = \sum_{\tau=0}^{\infty} \gamma^\tau P(s_{t+\tau} = s' \mid s_t = s).$$

$$V_{h,\gamma}(s_t) \rightarrow \sum_{\tau=0}^{\infty} \gamma^\tau \sum_s P(s_{t+\tau} = s \mid s_t) P(r_{t+\tau} > \theta_h \mid s_t, s_{t+\tau} = s)$$

$$V_{h,\gamma}(s_t) \rightarrow \sum_s \left(\sum_{\tau=0}^{\infty} \gamma^\tau P(s_{t+\tau} = s \mid s_t) \right) P(r > \theta_h \mid s) = SR^\gamma(s_t) \cdot \mathbf{r}_h$$

